

ZONDA hexapod

Very stable hexapod with high precision



KEY FEATURES

- Very high stability
- Payload capacity up to 400 kg
- Vacuum compatibility
- Large travel ranges
- Absolute linear encoders



APPLICATIONS

- Synchrotrons
- Tests laboratories
- Metrology
- Aeronautics and space
- Optics
- Semiconductors
- Instrumentation



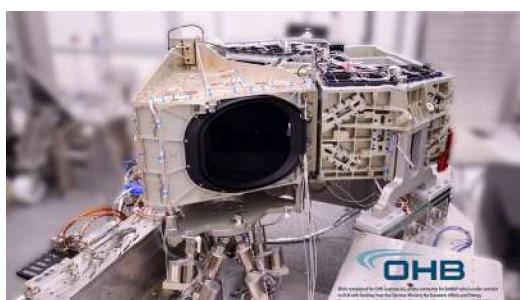
ISO5 clean room compatible hexapod to test space optical instruments for MTG (Meteosat Third Generation) satellites at BERTIN Technologies.



ZONDA Hexapod in a vacuum chamber with a mirror for optical calibration at Thales Alenia Space.



This HV ZONDA hexapod is used for the thermal vacuum tests and calibration of some of the cameras of PLATO mission at IAS.



This ZONDA S hexapod aligns two parts of a space telescope in an ISO5 clean room.



This ZONDA hexapod positions a coronograph in order to characterize it in a vacuum chamber at Liege Space Center (CSL).



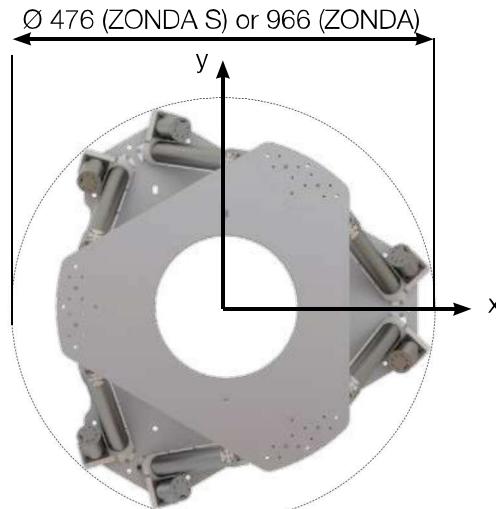
This ZONDA hexapod positions a laser interferometer (Zygo) in order to characterize the X-ray mirrors at Synchrotron SOLEIL.

| | ZONDA S | ZONDA |
|--|--|--|
| for small travel range | | for large travel range |
| Motion and positioning | | |
| Travel range Tx, Ty, (mm) | ± 50 | ± 200 |
| Travel range Tz (mm) | ± 25 | ± 150 |
| Travel range Rx, Ry (deg) | ± 10 | ± 20 |
| Travel range Rz (deg) | ± 20 | ± 20 |
| Resolution Tx, Ty, Tz (μm) | 0.1 | 0.1 |
| Resolution Rx, Ry, Rz (μrad) | 1.5 | 0.5 |
| Repeatability Tx, Ty, Tz (μm) | ± 0.25 | ± 0.25 |
| Repeatability Rx, Ry, Rz (μrad) | ± 2.5 | ± 1 |
| Speed Tx, Ty (mm/s) | 0.55 | 0.8 |
| Speed Tz (mm/s) | 0.4 | 0.4 |
| Speed Rx, Ry (deg/s) | 0.075 | 0.2 |
| Speed Rz (deg/s) | 0.12 | 0.4 |
| Mechanical properties | | |
| Stiffness X, Y (N/ μm) | 5 | 8.5 |
| Stiffness Z (N/ μm) | 50 | 30 |
| Payload capacity (kg) (vertical orientation / horizontal orientation) | 400 / 140 | 400 / 140 |
| Motor type | Stepper | Stepper |
| Encoder type | Absolute linear encoder | Absolute linear encoder |
| Miscellaneous | | |
| Operating temperature range (°C) | 0 to + 75 | 0 to + 75 |
| Materials | Aluminum, stainless steel, Invar, Peek | Aluminum, stainless steel, Invar, Peek |
| Size mobile platform (mm) | Ø 320 | Ø 720 |
| Height in middle position (mm) | 360 | 640 |
| Mass (kg) | 37 | 99 |
| Cable length (m) | < 5 | < 5 |
| Options | Clean room compatibility Vacuum compatibility Customized platform design Higher speed with brushless or DC motor Hand-held control unit Scalable size | |
| Controller | | |
| Controller type | ALPHA+ | |
| Interface | Ethernet | |
| Power supply | 110-240 VAC / 50-60 Hz | |

The performances are specified for single axis motions, with all other axes at midrange and for a rotation center in the middle of the mobile platform.



Hexapod in middle position



Datasheet subject to change without notice. All data are superseded by any new release. R220525