ANPz51/RES

compact, closed loop, linear, vertical stepper positioner with resistive encoder

Technical Specifications

Technology		
travel mechanism	inertial piezo drive	
Size and Dimensions		
footprint; height	15 x 18; 13.5 mm	
maximum size	15 x 18; 16 mm	
weight	13 g	
Coarse Positioning Mode	@ 300 K	@ 4 K
input voltage range	0 60 V	0 60 V
typical actuator capacitance	1.05 μF	0.15 μF
travel range (step mode)	2.5 mm	2.5 mm
typical minimum step size	50 nm	10 nm
maximum drive velocity	≈ 1 mm/s	
Fine Positioning Mode	@ 300 K	@ 4 K
input voltage range	0 100 V	0 150 V
fine positiong range	0 5 μm	0 0.8 μm
fine positioning resolution	sub-nm	sub-nm
Materials (non-magnetic)		
positioner body	titanium (upgrade option: beryllium copper)	
actuator	PZT ceramics	
connecting wires	insulated twisted pair, copper	
Load (@ ambient conditions)	mounting orientation: axis vertical	
maximum load	0.5 N (50 g)	
maximum dynamic force along the axis	1 N	
Mounting		
from the bottom	2 threads M2 x 5 mm	
load on top	4 threads M1.6 x 2 mm	
Article Numbers		
/RT Version	1003267	
/10/1/	1000000	

1003269

1003270

1003268 1003271

1003272

axis vertical 031 T 10 mK373 K 150 °C 1E-4 mbar 1E-8 mbar 5E-11 mbar resistive sensor 1 µW1 mW	
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5E-11 mbar resistive sensor 1 µW 1 mW	
resistive sensor 1 µW 1 mW	
1μW1mW	
1μW1mW	
full travel	
≈ 200 nm	
12 µm	
< 1%	
typically < 1.5 %	6 of travel range
ons	all /HV, /UHV Versions
g,	2-pole pin plug (PEEK),
2 mm,	ø 0.5 mm, d = 2 mm,
ith connector	30 cm cable with connector
ole plug	additional 3-pole plug (PEEK)
	VFT/HV, VFT/UHV
	12 µm < 1% typically < 1.5 % ons g, 2 mm, ith connector

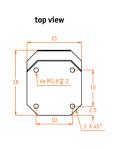
Technical Drawings

/HV Version

/LT Version

/UHV Version

/LT/HV Version /LT/UHV Version



inner position



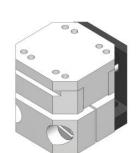
bottom view



outer position



3D view





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